



Precision Digital Presents

# An Introduction to Modbus<sup>®</sup> Communications

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## Agenda

1

What is Modbus?

2

Protocols, networks and terms

3

How does Modbus work?

4

When should I use Modbus?

5

Pros and Cons of Modbus

6

Practical cases

## Takeaways



Understand the fundamentals of the terms and difference between a network and communication protocol



Learn how Modbus works and how it's different from analog signals



Know the pros and cons of Modbus as a communication choice



Put it all together with a couple of real case scenarios

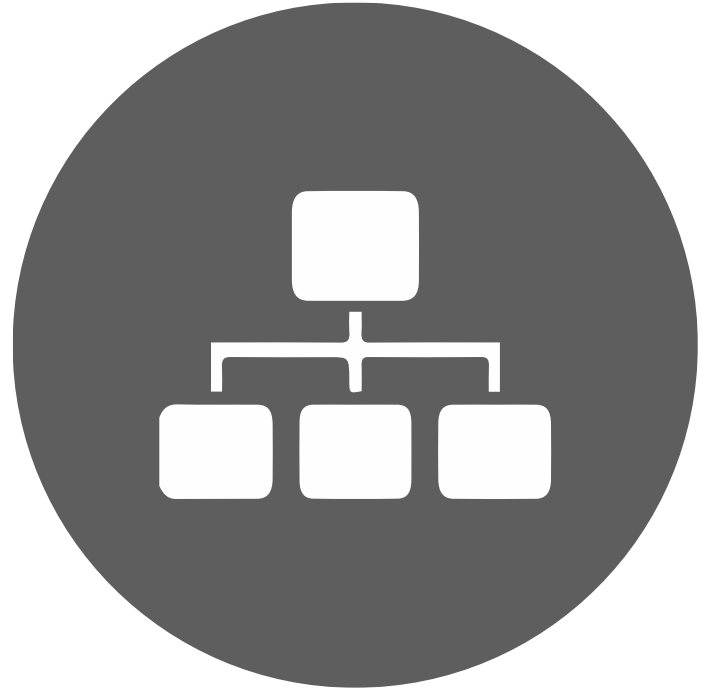
## Getting to know you

- Where are you located?
- What is your industry?
- What is your experience with Modbus?



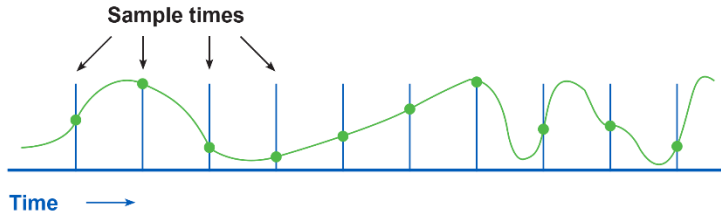
## What is Modbus?

- Digital communication for 2 or more devices
- An application-layer protocol
- Open source code
- Published by Schneider Electric



# Protocols, networks, and terms

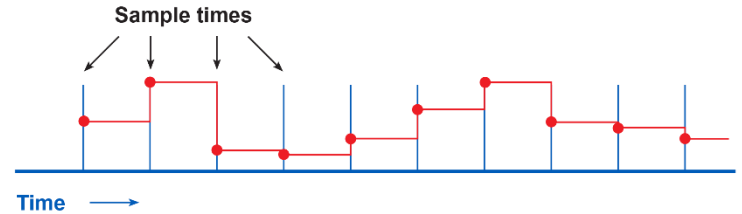
## Analog Input



## Analog Signals

- Analog signals have an infinite number of possible values over time.
- Example:
  - 12.9 mA
  - 4.563 mA

## Digital Output



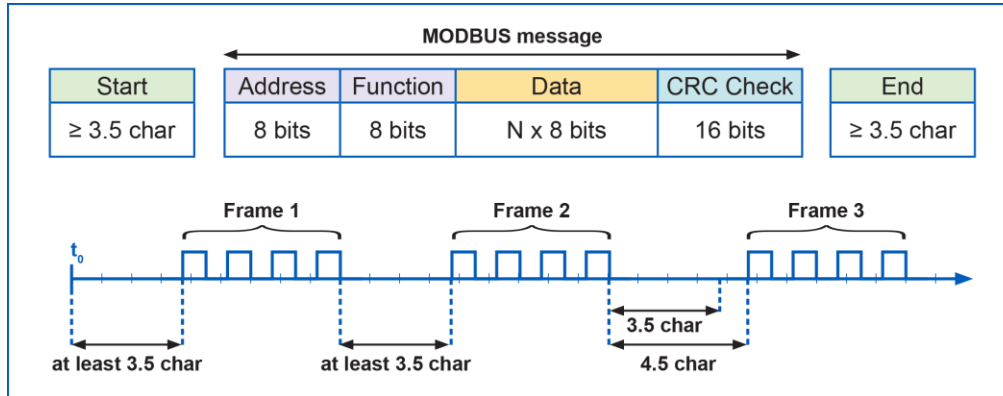
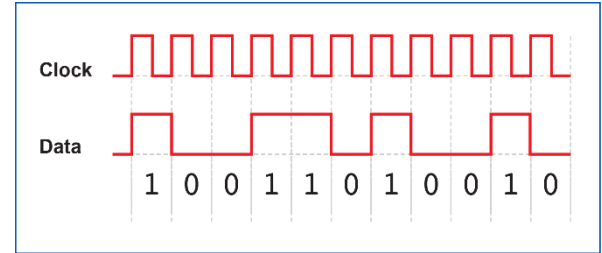
## Digital Signals

- Discrete number of values from 2 to billions determined by number of bits
- Vary with sample times

# Protocols, networks, and terms

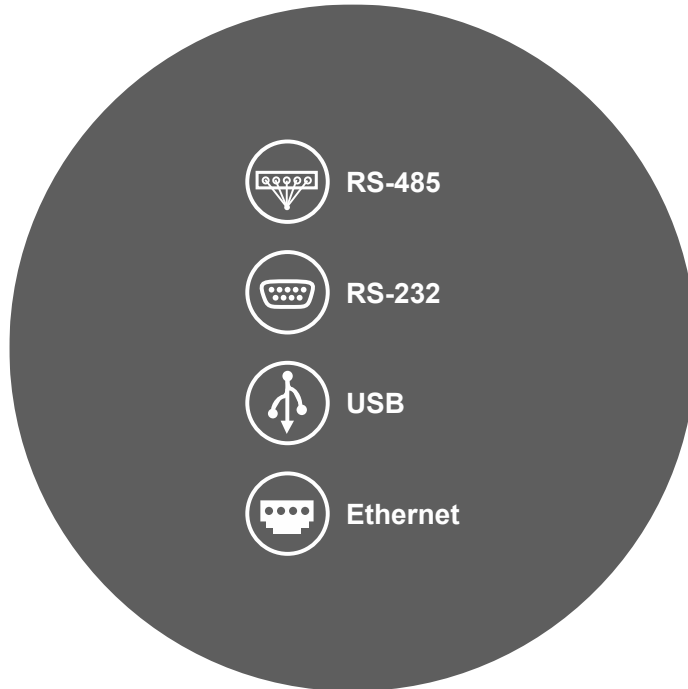
## Digital Communication via Packets

- Digital signal communicated 1 and 0 values
- This code is read and interpreted by the Protocol





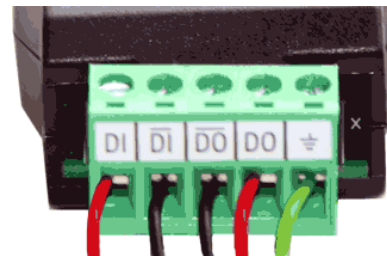
## Protocols, networks, and terms



- RS232, RS485, USB, Ethernet are types of networks and used with Modbus.
  - Different transmission mediums to send the Modbus Protocol
    - Modbus is the language being spoken
    - RS232, RS485, Ethernet, etc. are the medium, such as phone, VOIP, fax, letter, etc.
    - Different methods of communicating the same core language between two devices.

## Types of Networks

- RS-485
  - Full (5-wire) or half-duplex (3-wire)
  - Multi-drop
  - Up to 4,000 ft (1219 m).
  - Very common on industrial devices
  - Not common on computers
- RS-232
  - Usually 9-pin serial port
  - Usually only two devices
  - Up to 1,000 ft (305 m) are required.
  - Common on older desktop computers



**Example RS-485 5-Wire Connection**



**Example Female RS-232 Connection**

## Types of Networks (cont.)

- USB (Universal Serial Bus)
  - Various standard cables and connectors
    - Type A, Type B, mini, and micro
  - Less than 16 feet 5 inches (5 meters) without additional devices
  - Very common on computers
- Ethernet
  - Devices accessed anywhere on the network
  - Often everywhere in a facility
  - Web servers, virtual coms, etc. for global reach
  - Complicated to setup
  - Power over Ethernet options available



**Example USB Connectors**

## Questions?

- Please enter your questions in the 'Questions' window



## Common specifications and settings



Device address /  
Slave ID



Baud rate



Data format



Parity



Other

## Device Address / Slave ID

- Programmable for 1 – 247 devices
- Each device on the Modbus network must have a unique identifier.



## Baud rate



- Speed of communication in bits/second
- 300 – 19,200 bps
- Must be identical for all devices on the network

## Data format

- Configures the Modbus data packet
- Start bits & Stop bits
- Must match on all devices on the network





## Parity



- Even, odd or none
- Defines the data packet
- Should match on all devices

## Other specifications

- Byte-to-byte timeout
- Transmit delays
- Other



# Registers & tables

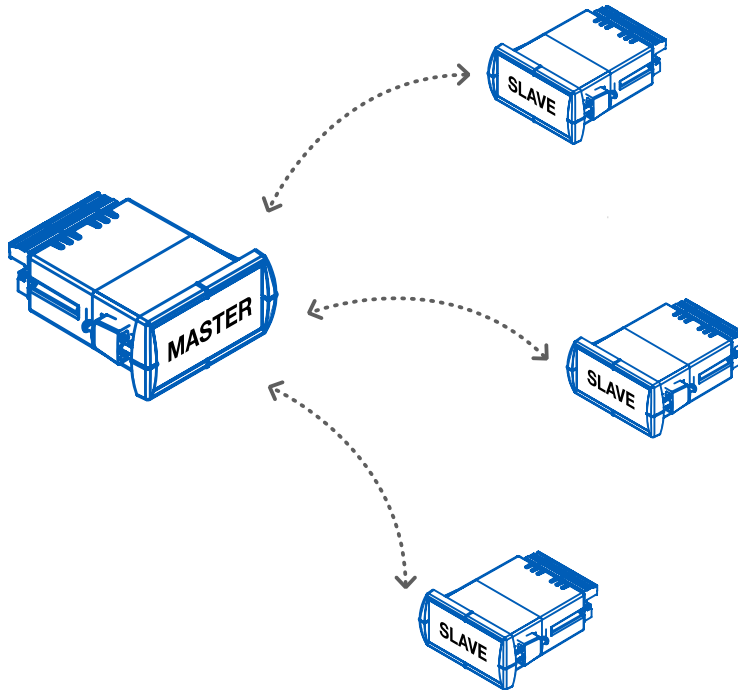
## PROVu<sup>®</sup> Modbus<sup>®</sup> Scanner Series Register Tables

## Serial Communication

Register <sup>1</sup>		Name	Access	Limits or Range <sup>2</sup>	Units	Data Type <sup>3</sup>	Function Code(s)	Comments																																																
Number	Address (Hex)																																																							
40001 – 40002	0 – 1 (0000 – 0001)	PV1 Display value	Read Only	-99999 to 999999	User defined	Floating point	03, 04	Represents the PV1 display value including the decimal point. Under Range = -99999, Over Range = 999999, and Open = -99999																																																
40003	2 (0002)	Alarm and Relay status	Read Only	1 = In Alarm 1 = relay energized	None	Word; Bits	03, 04	Read alarm status and energized/non-energized status of relays. Alm = Alarm. Rly = Relay. <table border="1" style="font-size: small; width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>Alm</td><td>Alm</td><td>Alm</td><td>Alm</td><td>Alm</td><td>Alm</td><td>Alm</td><td>Alm</td><td>Alm</td><td>Rly</td><td>Rly</td><td>Rly</td><td>Rly</td><td>Rly</td><td>Rly</td><td>Rly</td> </tr> <tr> <td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	Alm	Alm	Alm	Alm	Alm	Alm	Alm	Alm	Alm	Rly	Rly	Rly	Rly	Rly	Rly	Rly	8	7	6	5	4	3	2	1	8	7	6	5	4	3	2	1
15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0																																									
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40004	3 (0003)	Digital Inputs and Outputs status	Read Only	1 = Input selected 1 = Output active	None	Word; Bits	03, 04	Read the state of the digital inputs and outputs. <table border="1" style="font-size: small; width: 100%; text-align: center;"> <tr> <td>15</td><td>14</td><td>13</td><td>12</td><td>11</td><td>10</td><td>9</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>0</td> </tr> <tr> <td>DI</td><td>DI</td><td>DI</td><td>DI</td><td>DI</td><td>DI</td><td>DI</td><td>DI</td><td>DI</td><td>DO</td><td>DO</td><td>DO</td><td>DO</td><td>DO</td><td>DO</td><td>DO</td> </tr> <tr> <td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td><td>8</td><td>7</td><td>6</td><td>5</td><td>4</td><td>3</td><td>2</td><td>1</td> </tr> </table>	15	14	13	12	11	10	9	8	7	6	5	4	3	2	1	0	DI	DI	DI	DI	DI	DI	DI	DI	DI	DO	DO	DO	DO	DO	DO	DO	8	7	6	5	4	3	2	1	8	7	6	5	4	3	2	1
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40005 – 40006	4 – 5 (0004 – 0005)	Maximum Display value	Read Only	-99999 to 999999	User defined	Floating point	03, 04	Represents the Maximum display value, including the decimal point, since last power up or Max Value reset.																																																

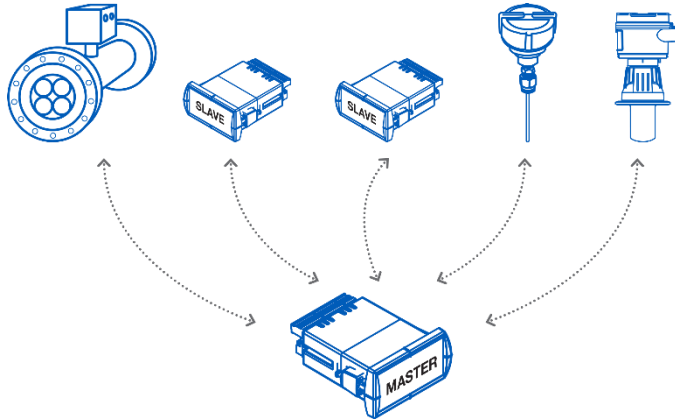
- Tables are a tool for programming the master device
- Tables are charts used to define the registers.
- Each register will have type and number.

## How does Modbus work?



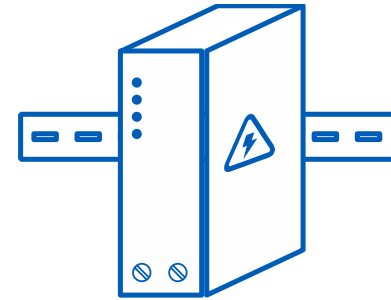
- Master and Slave devices
  - Master polls multiple slave devices to gather information
  - Slave devices cannot transmit information without a request
  - The master keeps communication organized
- Data is sent in a series of 1s and 0s called bits in packets
  - Data content is identified in tables and registers
- Modbus Map
  - Defines the data
  - Tells the Master where the data is stored
  - Tells the Master how the data is stored

## When should I use Modbus?



When more than one piece of data is required from multiple field devices

When a single field device gathers multiple useful PVs



When adequate power is available

## Pros and Cons of Modbus



### Pros

- Ability to use multivariate transmitters
- Better accuracy from digital signals
- Easy to add devices
- High noise immunity
- Centralized SCADA
- Open source
- Network versatility



### Cons

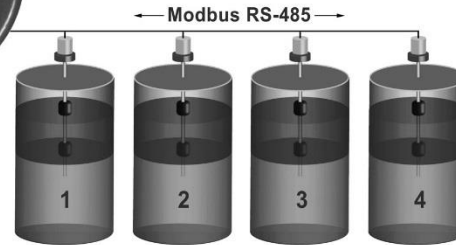
- More expensive than analog
- Complex to setup
- No way for slaves to report exceptions
- Limited to 247 devices
- No security of signal

## Practical Case 1: Level Monitoring of Oil & Water in Storage Tanks

Problem: Operator monitoring of top levels, oil/water interface levels, and temperature in storage tanks.

- PD6830-AX0-I-2 Modbus scanner as the Modbus master
- (4) MTS M-Series multivariable tank level gauges as *slaves*
- 3-wire half-duplex RS-485 used for the connections
  - Easy to wire
  - Long distances OK
  - Multidrop (5 devices on the network)

This solution displays product level, interface level, and temperature for each tank.



Tanks with Multivariable Level Transmitters

Fixed Serial Data Parameters	MTS M-Series Transmitter Data
Level Register	30001, 30002
Interface Register	30003, 30004
Ave Temp Register	30017, 30018
Data Type	Long Integer (2 registers), Binary, Signed
Byte Order	1234 (most significant digit register first)

The above parameters are taken from the MTS M-Series Modbus tables and used for programming the Scanner.

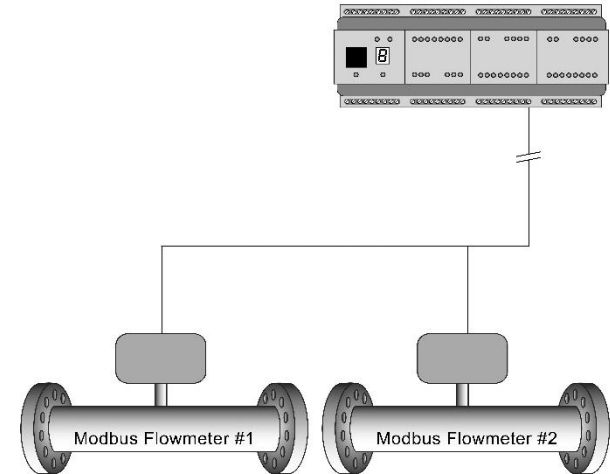
Serial Comm Parameters	Scanner	Tank 1 Transmitter	Tank 2 Transmitter	Tank 3 Transmitter	Tank 4 Transmitter
Address (Slave ID)	100	001	002	003	004
Baud Rate	4800 bps	4800 bps	4800 bps	4800 bps	4800 bps
Transmit Delay	50 ms	50 ms	50 ms	50 ms	50 ms
Parity/Stop Bits	None / 1	None / 1	None / 1	None / 1	None / 1

## Practical Case 2: Using Modbus to Poll Data From the Field

Problem: How to get exact, accurate data from two flow meters mounted far from the control room.

- Modbus on PLC allows for error-free rate and total information from the flowmeters
- Ethernet used as a communication method
  - Remote location OK
  - Already present in control room
  - Easy to add devices later

Serial Comm Parameters	Flow Transmitter 1	Flow Transmitter 2	Control Room PLC
Address (Slave ID)	100	200	001
Baud Rate	9600 bps	9600 bps	9600 bps
Transmit Delay	50 ms	50 ms	50 ms
Parity	Even, 1 Stop Bit	Even, 1 Stop Bit	Even, 1 Stop Bit



Fixed Serial Data Parameters	MTS M-Series Transmitter Data
Flow Data Register	30001, 30002
Totalizer Register	30016, 30017
Data Type	Long Integer (2 registers), Binary, Un-Signed
Byte Order	1234 (most significant digit register first)

The above parameters are taken from the flowmeter Modbus tables and used for programming the PLC.



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Practical cases

## Q & A

- Please enter your questions in the 'Questions' window
- Apologies if we do not get to your question today. We'll contact you offline with a response as soon as possible.



# Next Webinar – May 26th

## The Fundamentals of 4-20 mA Current Loops

- This webinar is designed as an introductory class for those who have to deal with 4-20 mA process signals but are not electrical engineers. This webinar will answer questions including:
  - What is a 4-20 mA current loop?
  - Why is this signal so popular?
  - How do I wire a 4-20 mA loop?
- Back by popular demand!



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